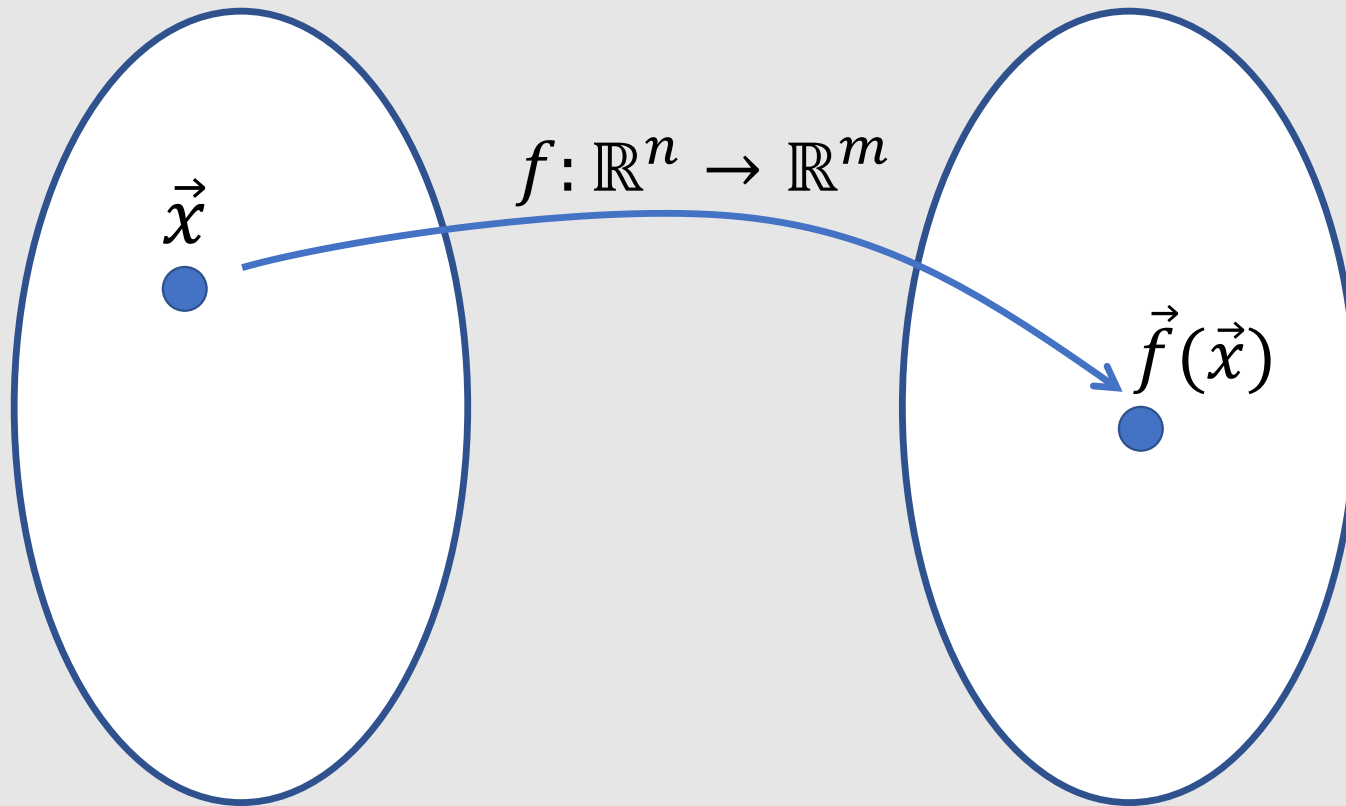


# Jacobian & Hessian

# Multivariate Function: High Dimensional Map

Input space  $\mathbb{R}^n$

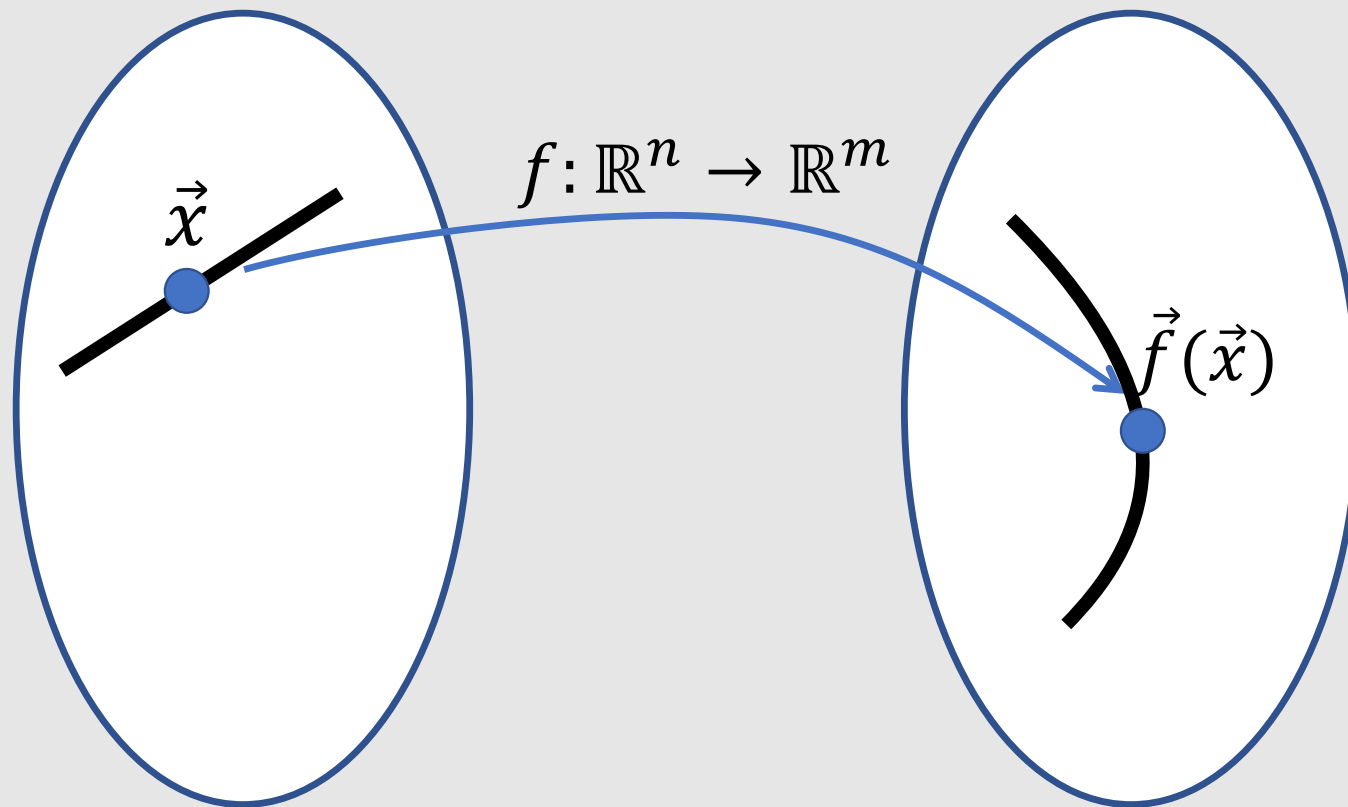
Output space  $\mathbb{R}^m$



# Trajectory of the Function

Input space  $\mathbb{R}^n$

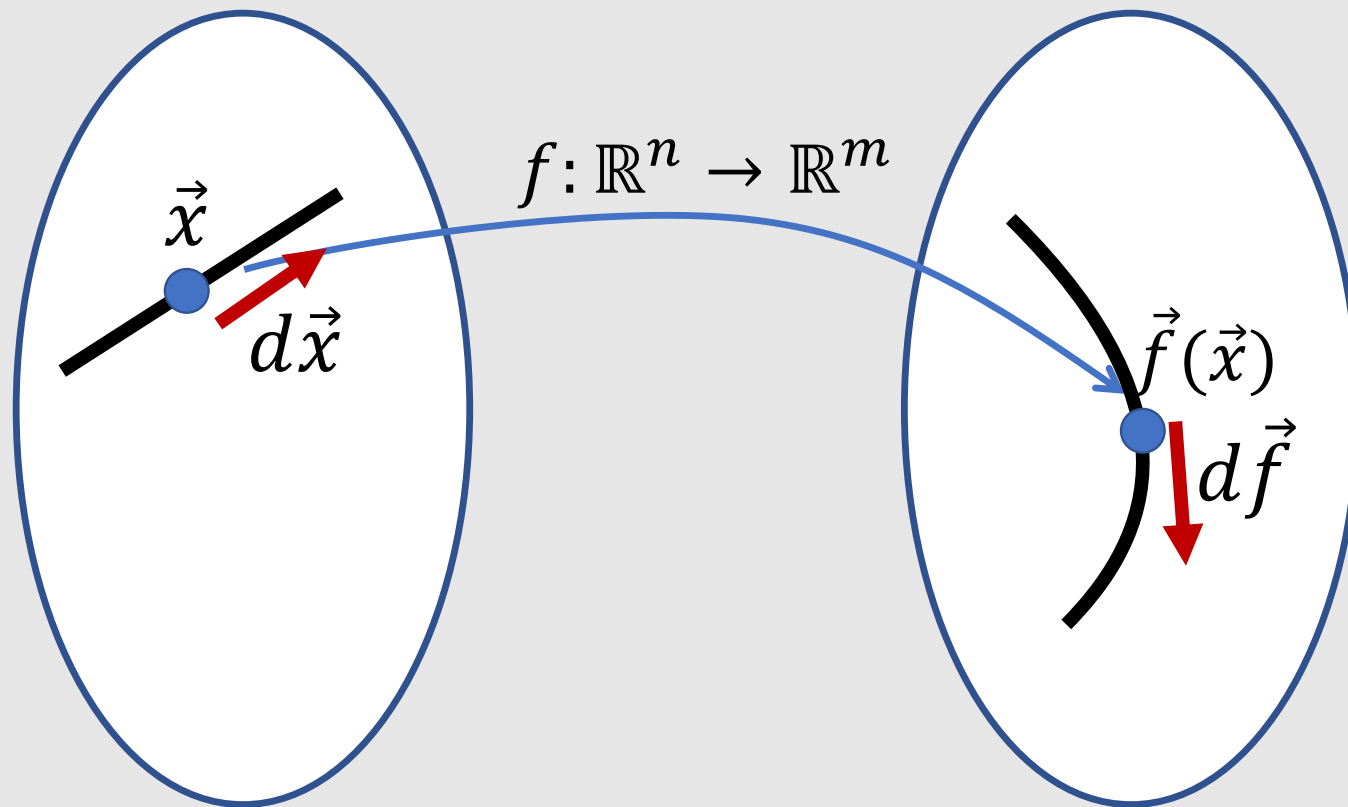
Output space  $\mathbb{R}^m$



# Differentiation of the Map

Input space  $\mathbb{R}^n$

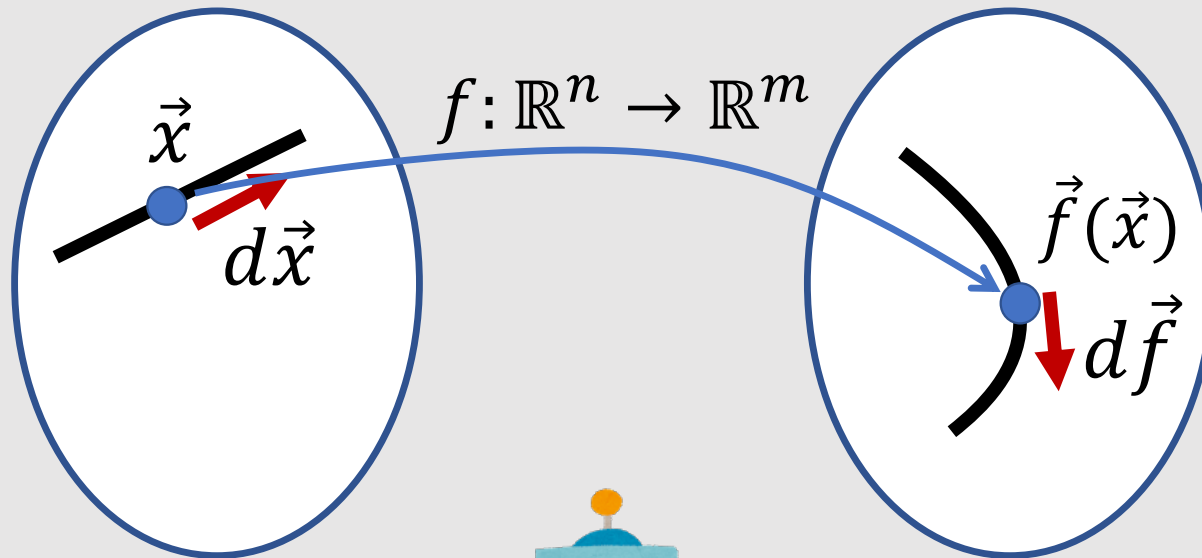
Output space  $\mathbb{R}^m$



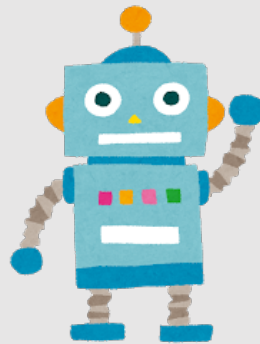
# Jacobian Matrix: Gradient of Map

Input space  $\mathbb{R}^n$

Input space  $\mathbb{R}^m$



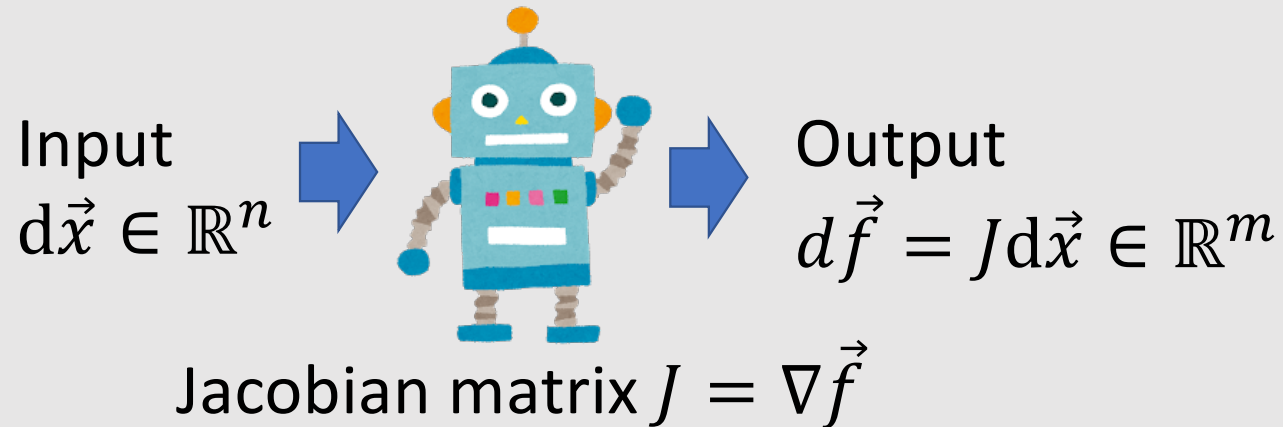
Input  
 $d\vec{x} \in \mathbb{R}^n$



Output  
 $d\vec{f} = Jd\vec{x} \in \mathbb{R}^m$

Jacobian matrix  $J = \nabla \vec{f}$

# Jacobian Matrix: Gradient of Map

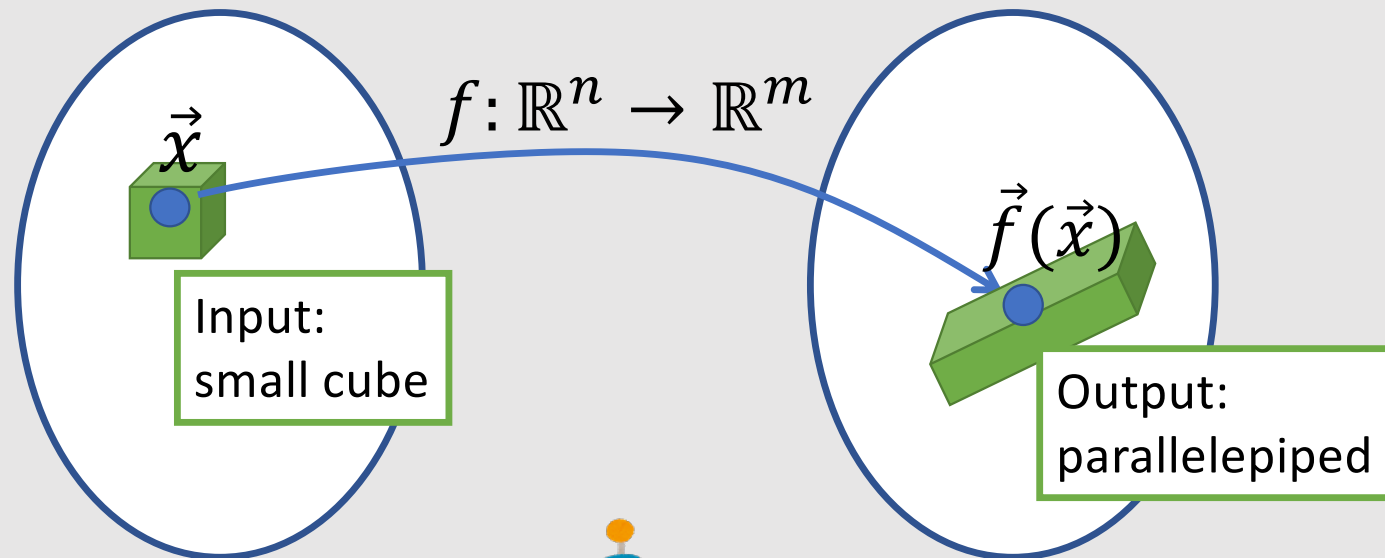


$$\mathbf{J} = \begin{bmatrix} \frac{\partial \mathbf{f}}{\partial x_1} & \dots & \frac{\partial \mathbf{f}}{\partial x_n} \end{bmatrix} = \begin{bmatrix} \nabla^T f_1 \\ \vdots \\ \nabla^T f_m \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

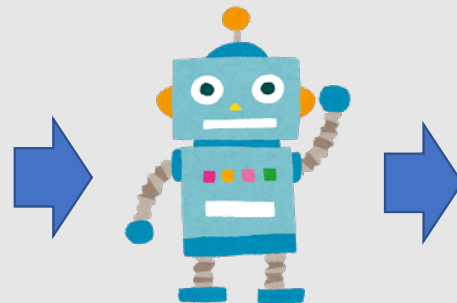
# Jacobian Determinant: Volume Change Ratio

Input space  $\mathbb{R}^n$

Input space  $\mathbb{R}^m$



Input  
volume:  $dv$



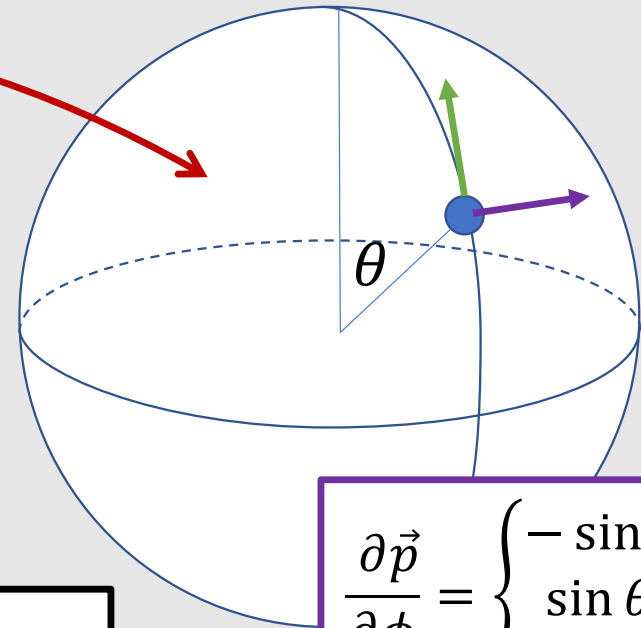
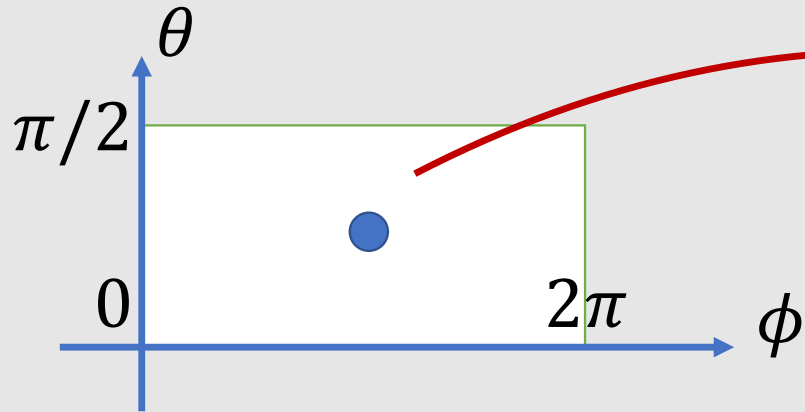
Output  
volume =  $\det(J) dv$

$$\text{Jacobian } J = \nabla \vec{f}$$

# Spherical Coordinate

$$\vec{p} = \begin{cases} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{cases}$$

$$\frac{\partial \vec{p}}{\partial \theta} = \begin{cases} \cos \theta \cos \phi \\ \cos \theta \sin \phi \\ -\sin \theta \end{cases}$$



$$\frac{\partial \vec{p}}{\partial \phi} = \begin{cases} -\sin \theta \sin \phi \\ \sin \theta \cos \phi \\ 0 \end{cases}$$

$$\det(J) = \left| \frac{\partial \vec{p}}{\partial \theta} \times \frac{\partial \vec{p}}{\partial \phi} \right| = |\sin \theta \vec{p}| = \sin \theta$$



# Hessian Matrix: Jacobian Matrix for Gradient

- Second derivative of a scalar function  $f(\vec{x})$

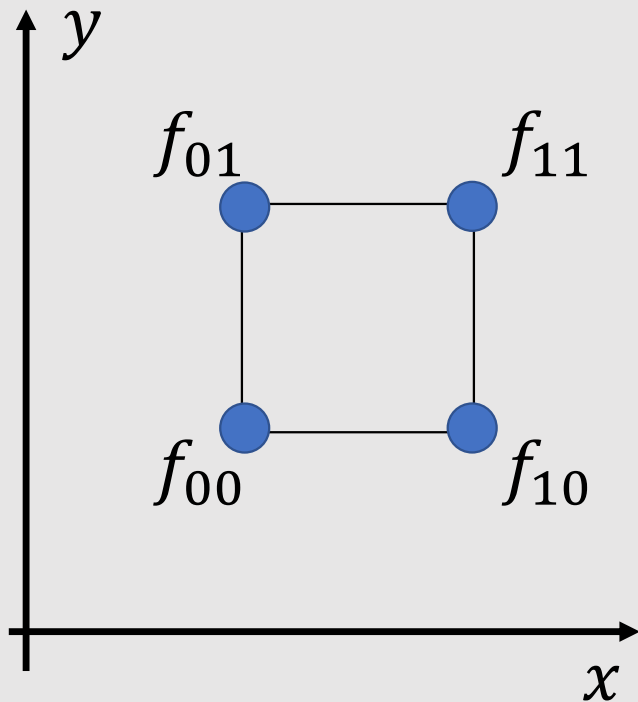
$$\mathbf{H}_f = J(\nabla f(\vec{x}))$$

$$(\mathbf{H}_f)_{i,j} = \frac{\partial^2 f}{\partial x_i \partial x_j}.$$

$$\mathbf{H}_f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix},$$

# Symmetry of Hessian

- Hessian is symmetric if  $f(\vec{x})$  is continuous



$$\frac{\partial}{\partial x} \left( \frac{\partial f}{\partial y} \right) \approx (f_{11} - f_{10}) - (f_{01} - f_{00})$$

$$\frac{\partial}{\partial y} \left( \frac{\partial f}{\partial x} \right) \approx (f_{11} - f_{01}) - (f_{10} - f_{00})$$

equal

Symmetric Matrix

$$\mathbf{H}_f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix}$$