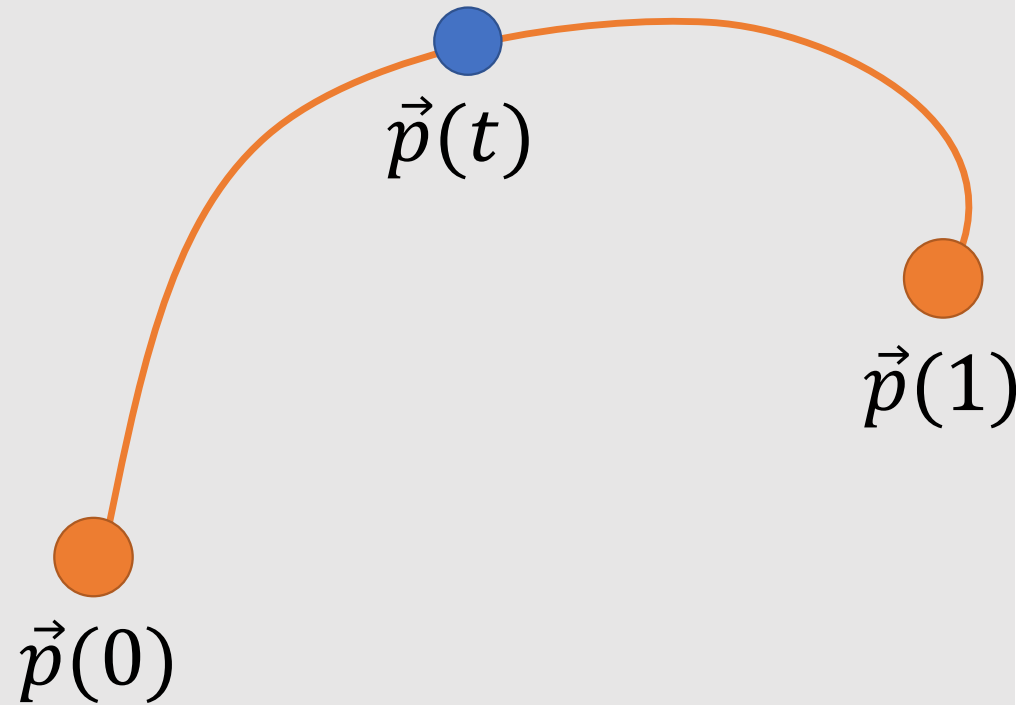


# Parametric Curve

# Parametric Curve



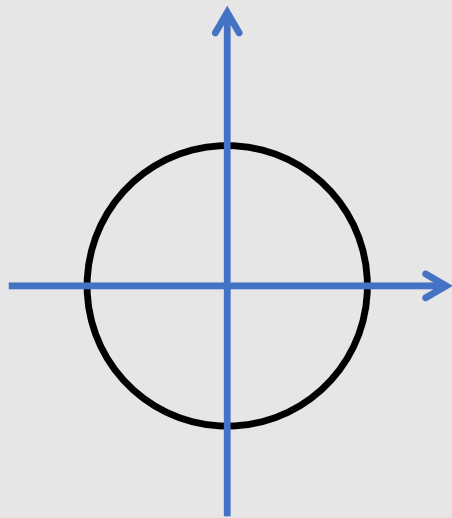
mapping



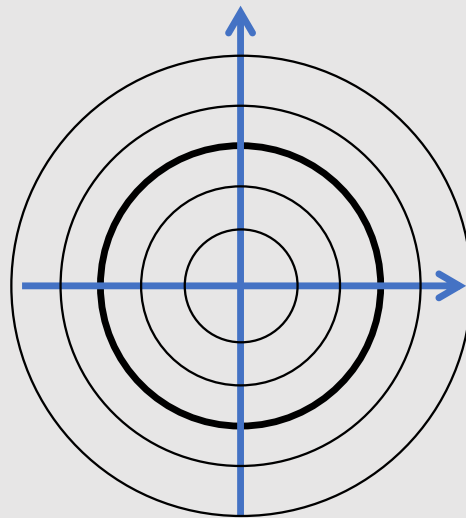
# Example of Parametric Representation

*Implicit  
Representation*

$$|x^2 + y^2| = 1$$

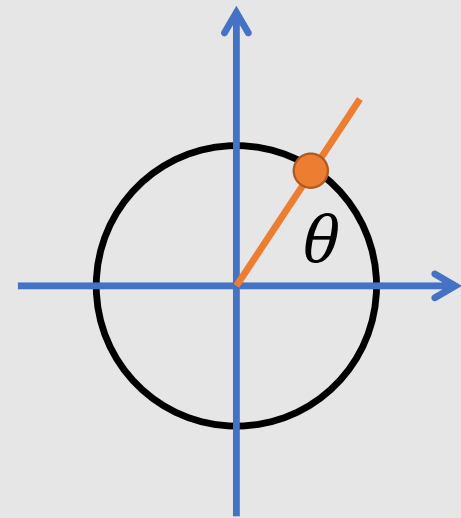


$$f(x, y) = |x^2 + y^2| - 1$$

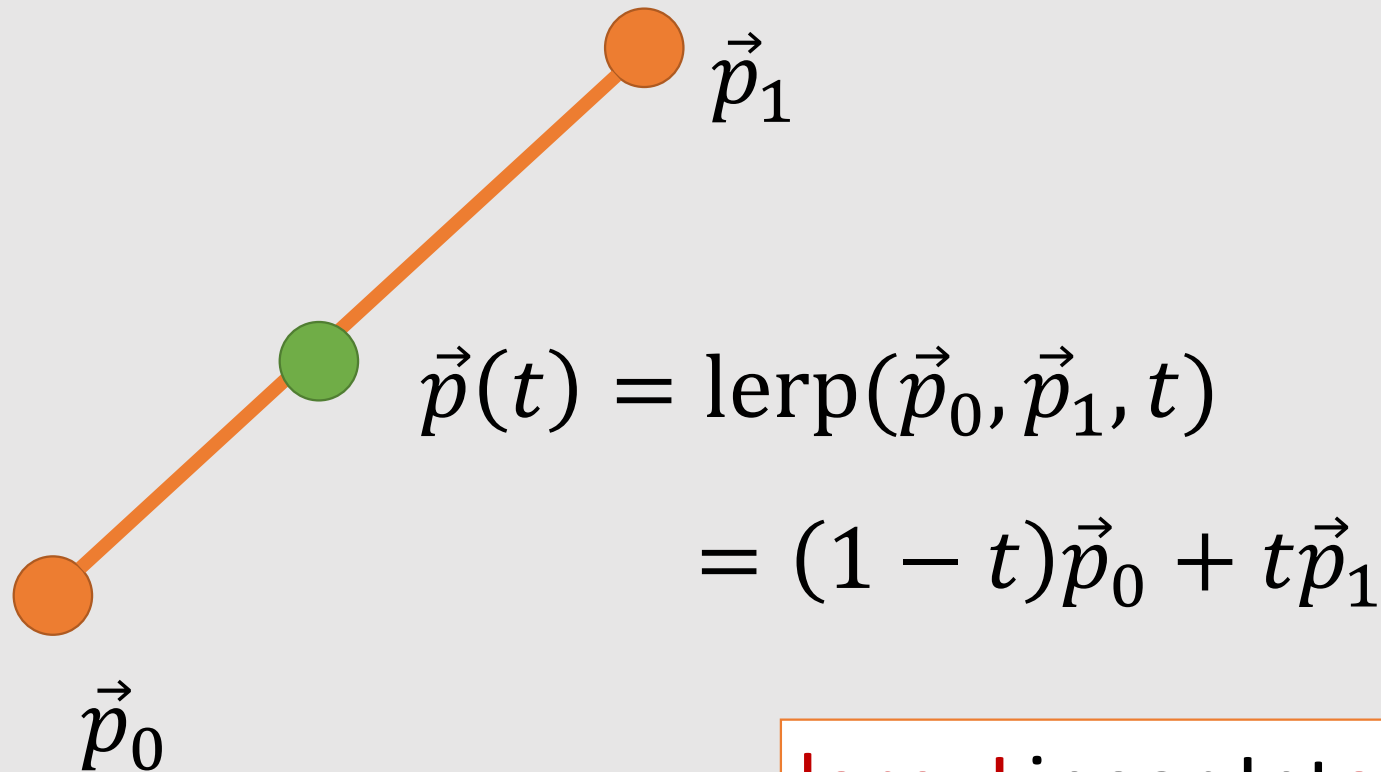


*Parametric  
Representation*

$$\begin{cases} x = \cos(2\pi\theta) \\ y = \sin(2\pi\theta) \end{cases}$$



# Simplest Parametric Curve: Line

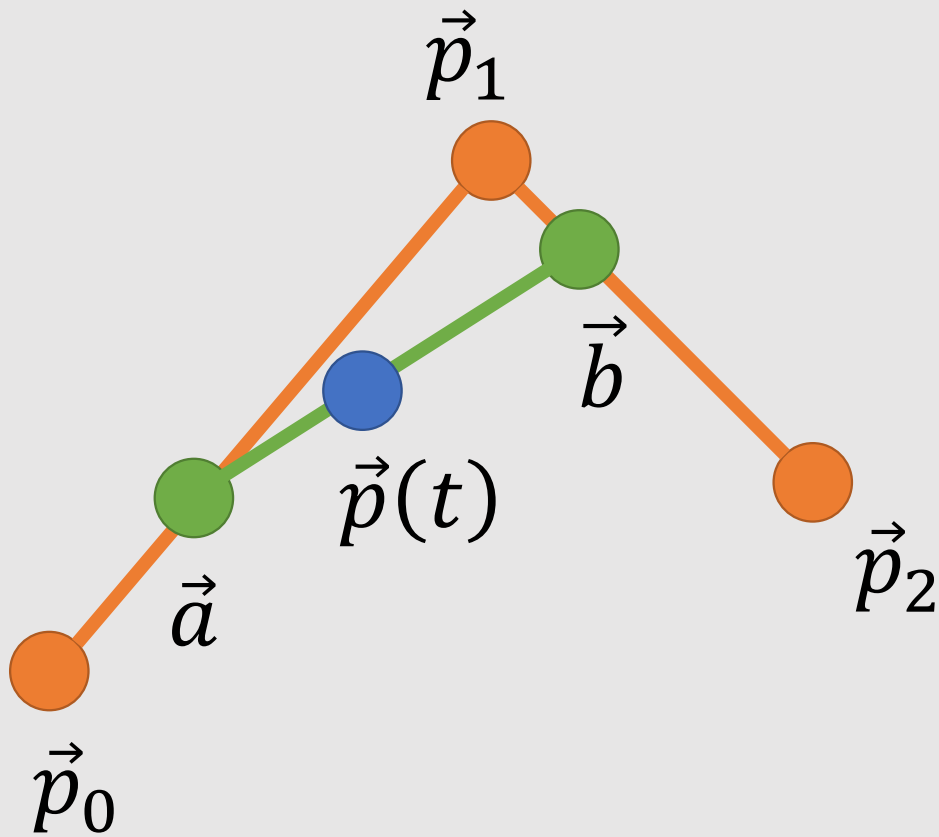


$$\vec{p}(t) = \text{lerp}(\vec{p}_0, \vec{p}_1, t)$$

$$= (1 - t)\vec{p}_0 + t\vec{p}_1$$

lerp=Linear Interpolation

# Quadratic Bézier Curve

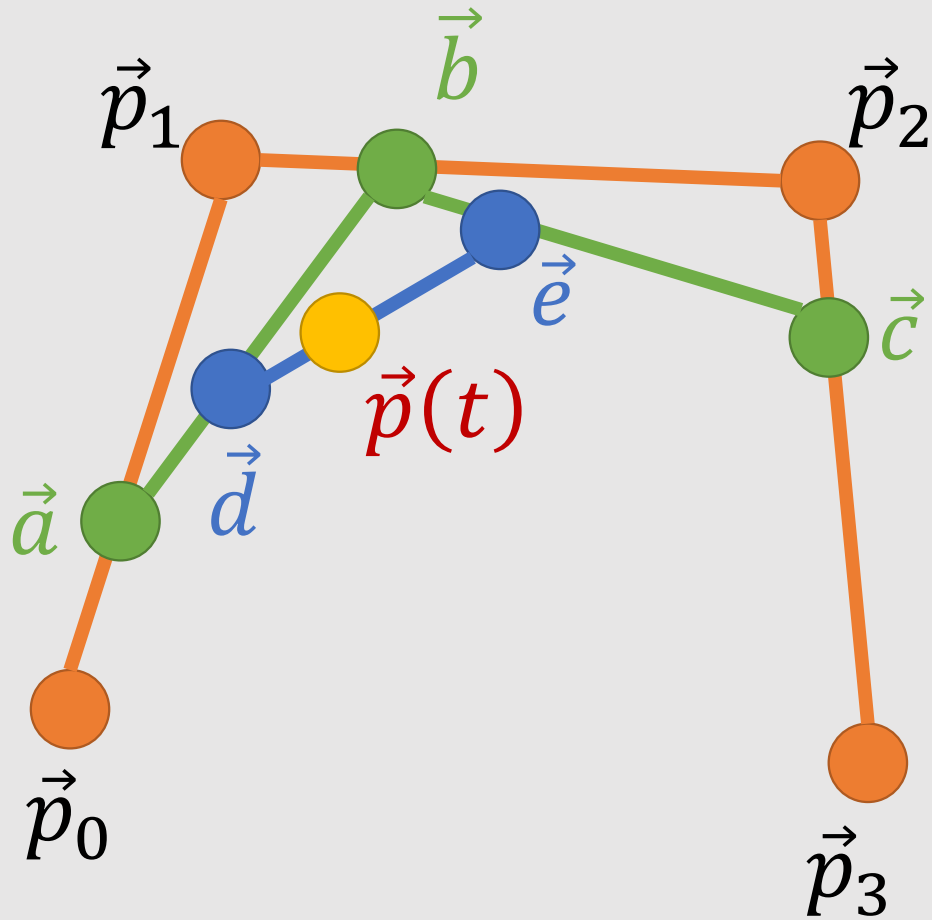


$$\vec{a}(t) = \text{lerp}(\vec{p}_0, \vec{p}_1, t)$$

$$\vec{b}(t) = \text{lerp}(\vec{p}_1, \vec{p}_2, t)$$

$$\vec{p}(t) = \text{lerp}(\vec{a}, \vec{b}, t)$$

# Cubic Bézier Curve



$$\vec{a}(t) = \text{lerp}(\vec{p}_0, \vec{p}_1, t)$$

$$\vec{b}(t) = \text{lerp}(\vec{p}_1, \vec{p}_2, t)$$

$$\vec{c}(t) = \text{lerp}(\vec{p}_2, \vec{p}_3, t)$$

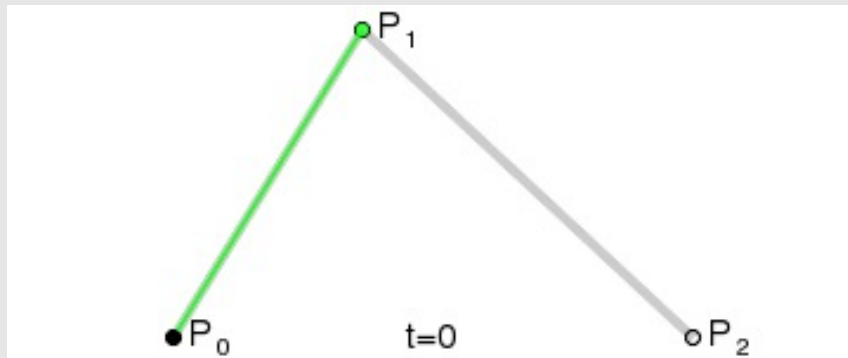
$$\vec{d}(t) = \text{lerp}(\vec{a}, \vec{b}, t)$$

$$\vec{e}(t) = \text{lerp}(\vec{b}, \vec{c}, t)$$

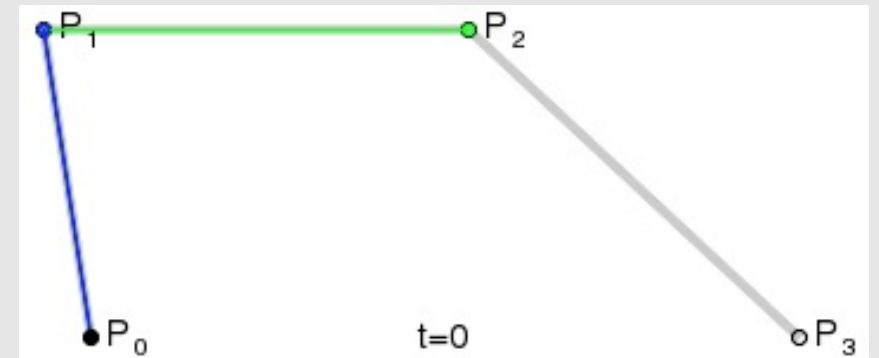
$$\vec{p}(t) = \text{lerp}(\vec{d}, \vec{e}, t)$$

# De Casteljau's Algorithm

*Quadratic Bézier Curve*



*Cubic Bézier Curve*



# Bernstein Polynomial Form

$$\vec{a}(t) = (1 - t)\vec{p}_0 + t\vec{p}_1$$

$$\vec{b}(t) = (1 - t)\vec{p}_1 + t\vec{p}_2$$

$$\vec{c}(t) = (1 - t)\vec{p}_2 + t\vec{p}_3$$

$$\vec{d}(t) = (1 - t)\vec{a} + t\vec{b}$$

$$\vec{e}(t) = (1 - t)\vec{b} + t\vec{c}$$

$$\vec{p}(t) = (1 - t)\vec{d} + t\vec{e}$$



$$\begin{aligned}\vec{p}(t) = & \vec{p}_0\{(1 - t)^3\} + \\ & \vec{p}_1\{3t(1 - t)^2\} + \\ & \vec{p}_2\{3(1 - t)^2t\} + \\ & \vec{p}_3\{t^3\}\end{aligned}$$

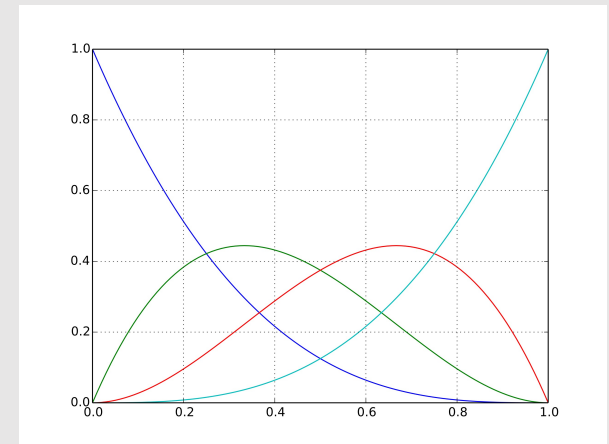
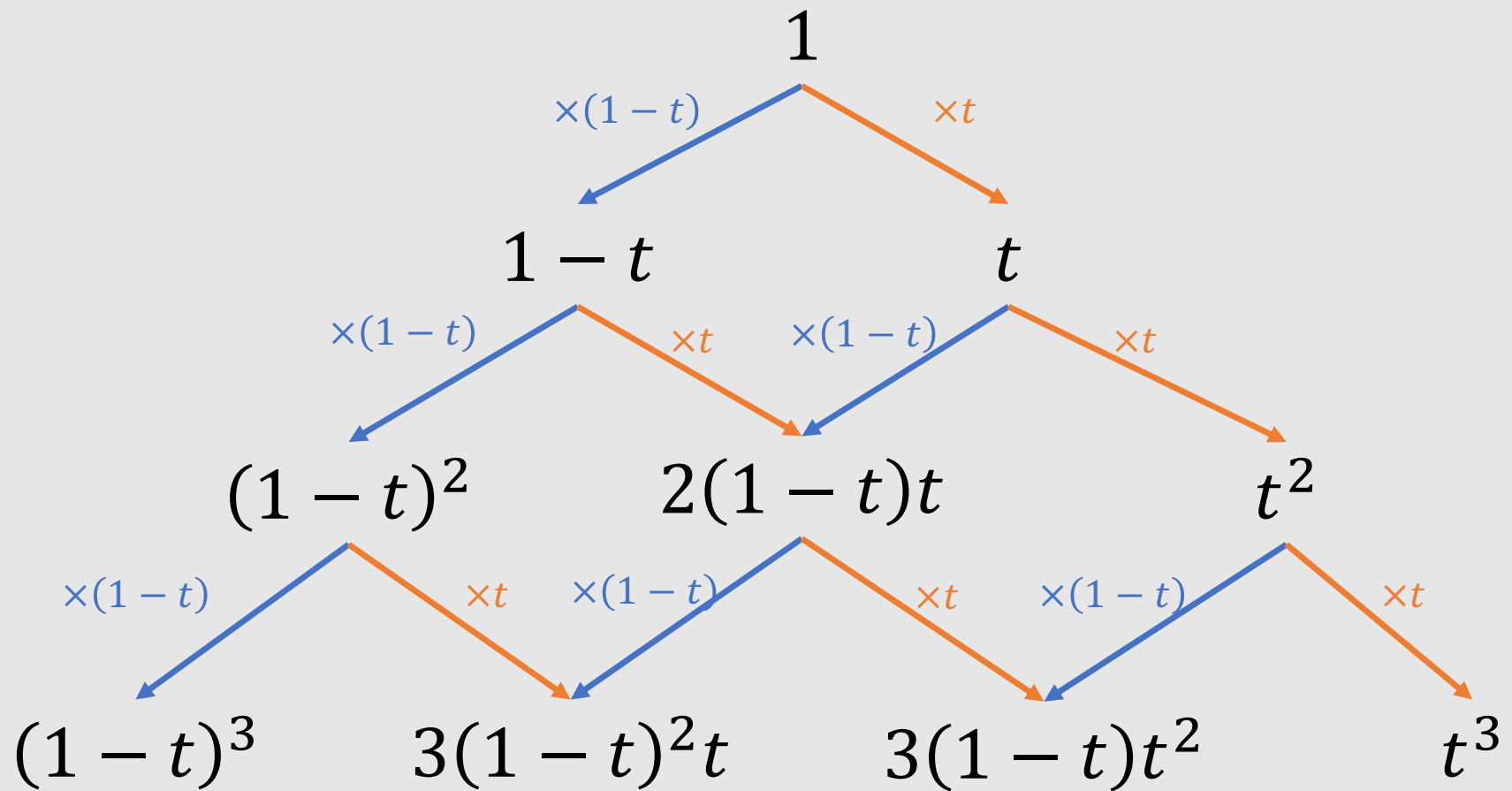


Image Credit: Ben FrantzDale@Wikipedia



# Bernstein's Polynomial



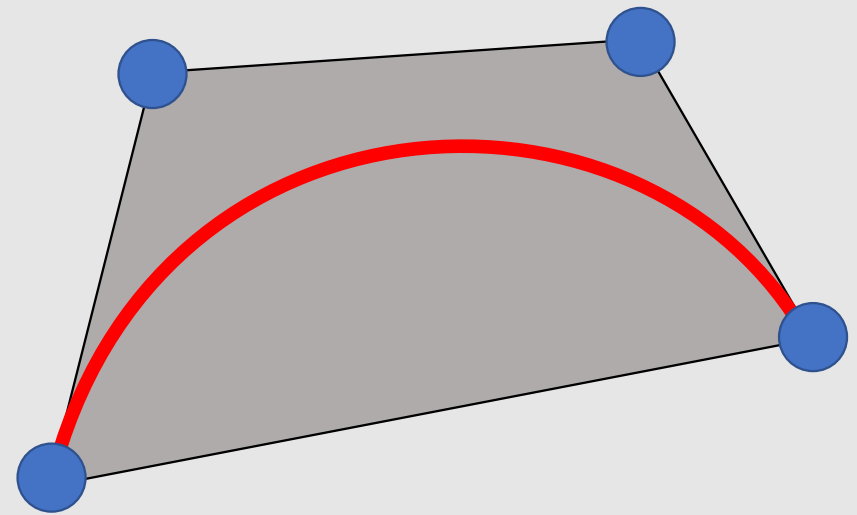
# Bezier Curve & Convex Hull of Ctrl. Points

$$p(t) = \sum w_i(t) \vec{p}_i$$

$$\sum w_i(t) = 1$$

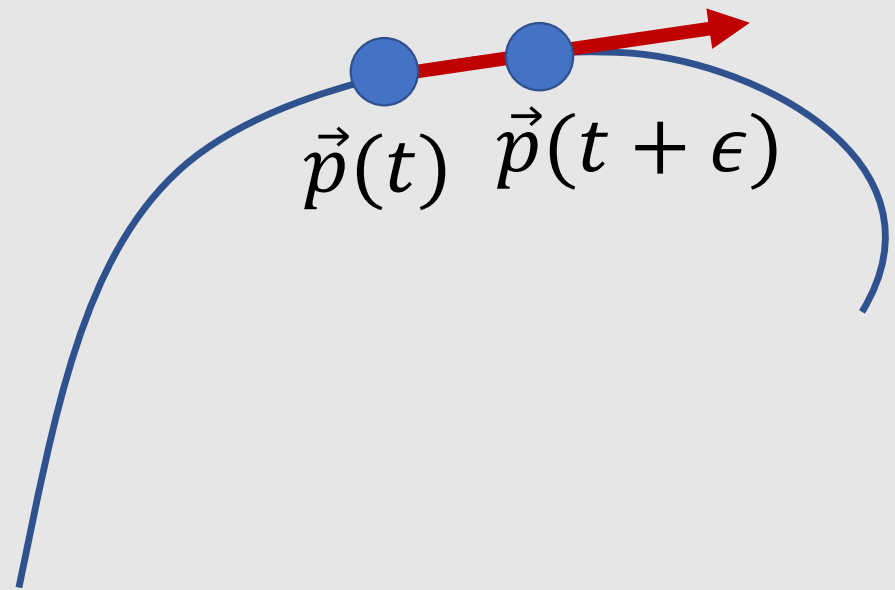
$$0 \leq w_i(t) \leq 1$$

Bézier curve is always  
inside the convex hull



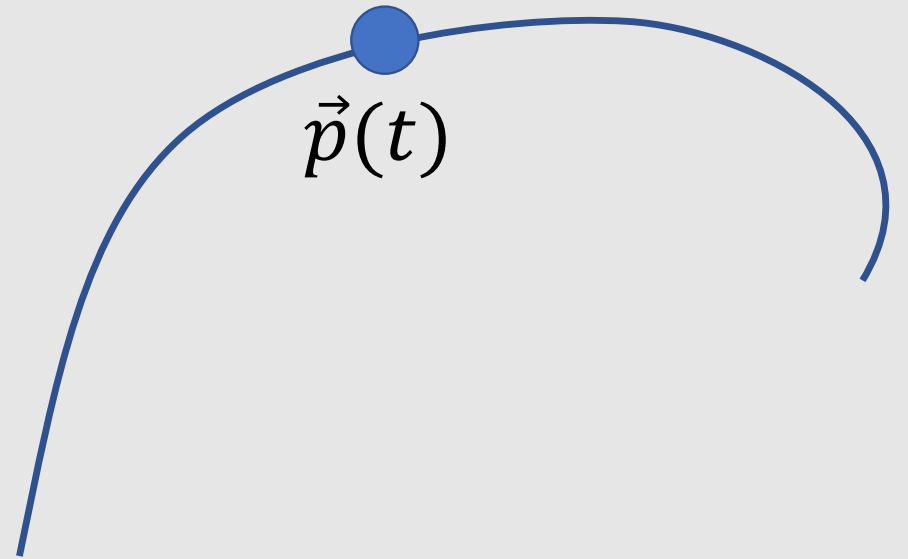
# Derivative of a Parametric Curve = Tangent

$$\vec{p}(t)' = \lim_{\epsilon \rightarrow 0} \frac{\vec{p}(t+\epsilon) - \vec{p}(t)}{\epsilon}$$



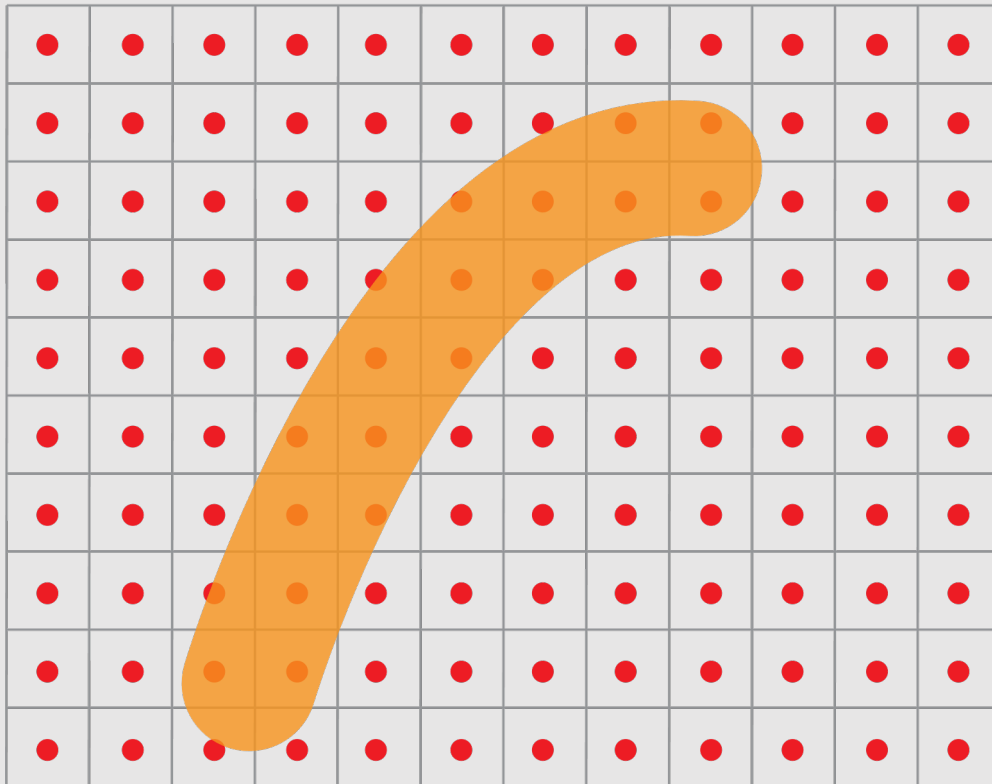
# Length of a Parametric Curve

$$\text{Length} = \int_0^1 |\vec{p}'(t)| dt$$



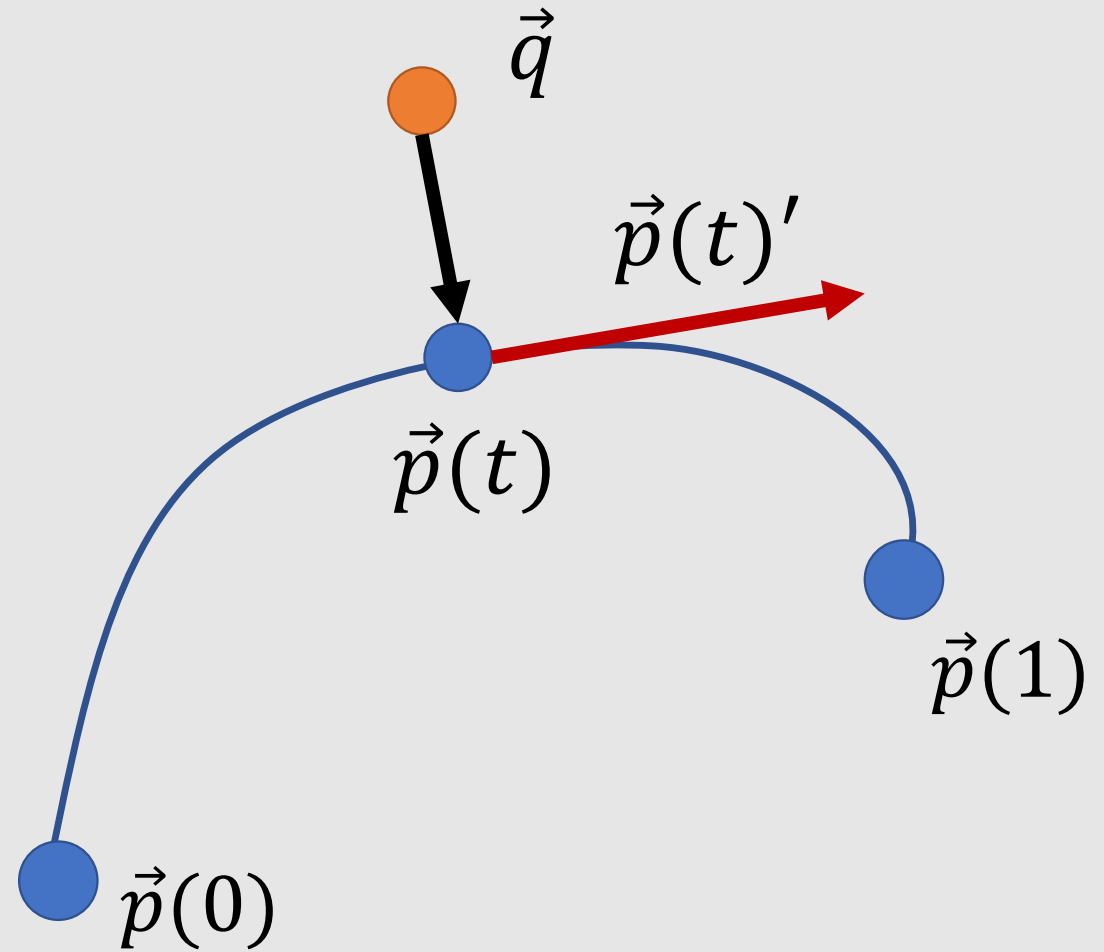
# Rasterization of Curve

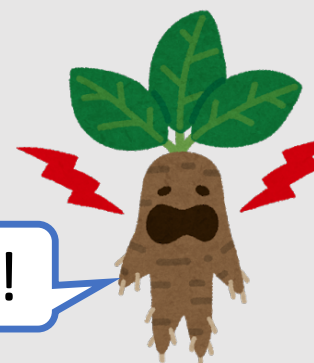
- Need to compute distance to the curve from each pixel



# Distance to the Curve

$$\text{Distance} = \min_{t \in [0,1]} \|\vec{q} - \vec{p}(t)\|^2$$





Find the root!

# **Sturm's Method**

# Horner's Method

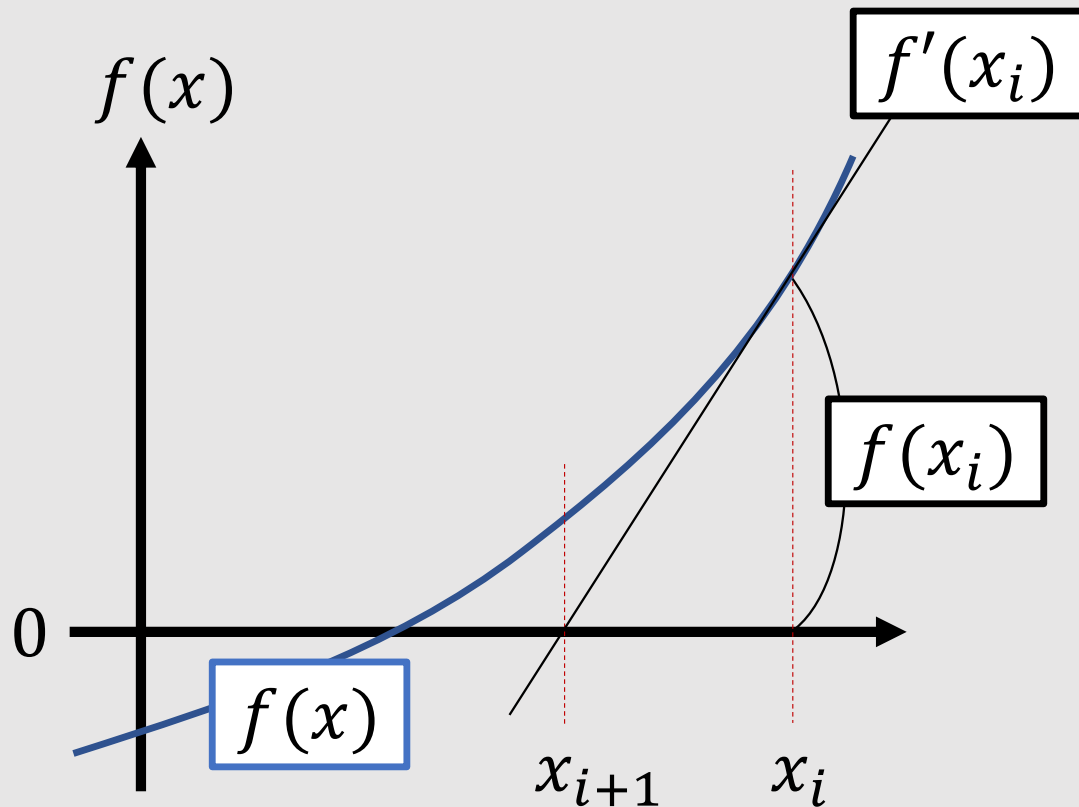
- Fast evaluation of polynomial:  $n$  multiplications and  $n$  additions

$$f(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \cdots + a_nx^n$$

$$= a_0 + x \left( a_1 + x \left( a_2 + x \left( a_3 + \cdots + x \left( a_{n-1} + xa_n \right) \right) \right) \right)$$



# Newton's Method to Find the **Root**



To find  $x$  where  $f(x) = 0$

Iterate:

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

# Division of Polynomial



divisor

$$\begin{array}{r} 5 \leftarrow \text{quotient} \\ 5 \overline{) 27} \leftarrow \text{quotient} \\ \underline{25} \\ 2 \leftarrow \text{remainder} \end{array}$$

$$27 = 5 \times 5 + 2$$

$$\deg(2) < \deg(5)$$

$$\begin{array}{r} Q(x) \\ g(x) \overline{) f(x)} \\ \hline R(x) \end{array}$$

$$f(x) = Q(x)g(x) + R(x)$$

$$\deg(R(x)) < \deg(g(x))$$

# Example of Polynomial Division



$$\begin{array}{r} Q(x) \\ g(x) \overline{) f(x)} \\ \hline R(x) \end{array}$$

$$f(x) = ax^2 + bx + c$$

$$g(x) = dx + e$$

$$f(x) = Q(x)g(x) + R(x)$$

$$\deg(R(x)) < \deg(g(x))$$

# Sturm Sequence & Sturm's Method

## *Sturm sequence*

$$f_0 = f$$

$$f_1 = f_0'$$

$$f_2 = -\text{rem}(f_0, f_1)$$

⋮

$$f_{i+1} = -\text{rem}(f_{i-1}, f_i)$$

⋮

Sturm Number



number of sign  
change:  $N(x)$

$x$	$f_0(x)$	$f_1(x)$	$f_2(x)$	$f_3(x)$	
$a$	-	+	-	+	3
$b$	+	-	-	-	1

$$\begin{aligned} \text{Number of roots in } [a, b) &= N(a) - N(b) \\ &= 3 - 1 = 2 \end{aligned}$$

# Bisection Method to Find Root

- Narrowing the range by half

